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Members and affiliates are Gabriel Bousquet (g_b@mit.edu) Soon-Jo Chung (sjchung@mit.edu) Joanna Cohen (joannac@mit.edu) Khalid El-Rifai (elrifai@mit.edu) Winfried Lohmiller (wslhml@mit.edu) Quang-Cuong Pham (cuong@mit.edu) Jonathan Soto (j_soto@mit.edu) Nicolas Tabareau (tabareau@mit.edu) JEAN-JACQUES SLOTINE - Mechanical Engineering Applied Nonlinear Control JEAN-JACQUES E. SLOTINE Massachusetts Institute of Technology ... Introduction 1 1.1 Why Nonlinear Control ? 1 1.2 Nonlinear System Behavior 4 1.3 An Overview of

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Analysis and Control" (Asada and Slotine, Wiley, 1986), and "Applied Nonlinear Control" (Slotine and Li, Prentice-Hall, 1991) and is one of the most cited researcher in both systems science and robotics. He was a member of the French National Science Council from 1997 to 2002, and a member of Singapore's

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function candidate for autonomous nonlinear systems of the ____ Chapter 3 Fundamentals of Lyapunov Theory 15 Applied Nonlinear Control Nguyen Tan Tien - 2002.3 ____ form (3.2), namely, $V = f^T f$. The basic idea of the method is function for this system.